

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	17052	(robot mechanical machine) and (arm limb appendage) and (hold grasp clutch grip clasp) and (proximal) and (distal) and (orientation bearing direction coordination position)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/07/27 12:31
L2	1161	(robot mechanical machine) and (arm limb appendage) and (hold grasp clutch grip clasp) and (proximal) and (distal) and (orientation bearing direction coordination position) same container	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/07/27 12:31
L3	610	(robot machine) and (arm limb appendage) and (hold grasp clutch grip clasp) and (proximal) and (distal) and (orientation bearing direction coordination position) same container	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/07/27 12:32
L4	110	(robot machine) and (arm limb appendage) and (hold grasp clutch grip clasp) and (proximal) and (distal) and (orientation bearing direction coordination position) and (visual ccd camera optical) same container	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/07/27 12:33
L5	12	(robot android machine) same (arm limb appendage) same (hold grasp clutch grip clasp) same (visual ccd camera optical) same (orientation bearing direction coordination position) same (container)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/07/27 12:34
L6	69	(robot android machine) same (arm limb appendage) same (hold grasp clutch grip clasp) same (visual ccd camera optical) same (orientation bearing direction coordination position) same (container)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/07/27 12:34
S1	3	("6597971") or ("4402053") or ("4613269").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2007/07/27 08:17
S2	1	("20040186624").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2007/07/27 08:18